

# Stochastic Evaluation of Large Interdependent Composed Models Through Kronecker Algebra and Exponential Sums

G. Masetti, L. Robol, S. Chiaradonna and F. Di Giandomenico

ISTI-CNR Pisa, University of Pisa

# Presentation outline

- Context (state of the art)
- Focus of the analysis and KAES methodology
- Case study and numerical evaluation
- Conclusions and future work

# Focus of the analysis

- Stochastic Petri Nets context
- Irreducible CTMCs
- CTMCs with **absorbing states**

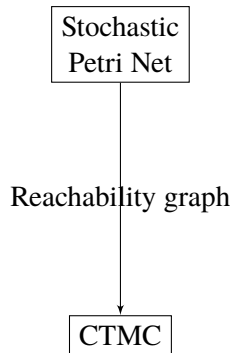
# Focus of the analysis

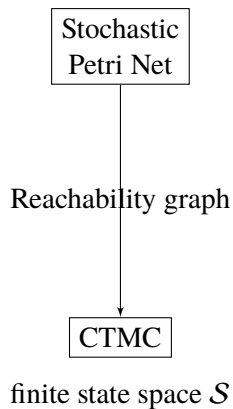
- Stochastic Petri Nets context
- Irreducible CTMCs
- CTMCs with **absorbing states**
  - Definition of reward structure is crucial
  - System comprising a large number of weakly interdependent components
- **Goal 1:** extend the class of systems for which Mean Time To Absorption can be evaluated
- **Goal 2:** safe evaluation of MTTA (lower bound)
- **Goal 3:** foresee a road map to evaluate also transient measures

# Structure of this presentation

- List of **problems** we encountered when adapting techniques for the evaluation of
  - steady-state probability vector (irreducible CTMCs)
  - transient measures (relatively small CTMCs)to the solution of CTMCs with absorbing states
- Often solving a given problem produces a new set of problems
- For each problem I will discuss the **proposed solution**, observing that a complete comparison among available solutions is out of the paper scope

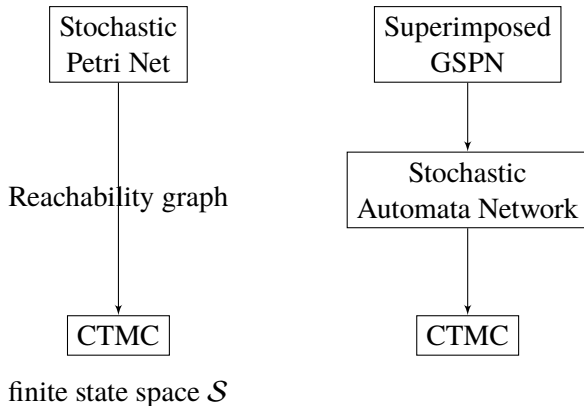
# Context



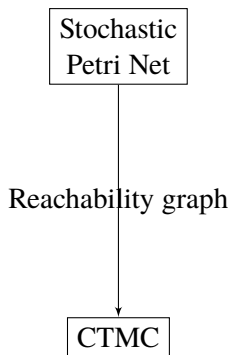


infinitesimal generator  $Q \in \mathbb{R}^{|\mathcal{S}| \times |\mathcal{S}|}$



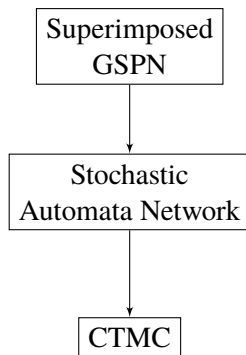


infinitesimal generator  $Q \in \mathbb{R}^{|\mathcal{S}| \times |\mathcal{S}|}$



finite state space  $\mathcal{S}$

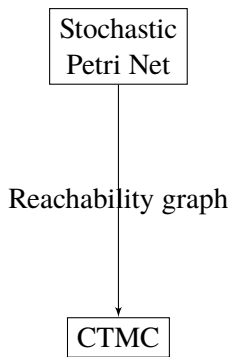
infinitesimal generator  $Q \in \mathbb{R}^{|\mathcal{S}| \times |\mathcal{S}|}$



small state spaces  $\mathcal{S}^{(1)}, \dots, \mathcal{S}^{(n)}$

potential states  $\mathcal{PS} = \mathcal{S}^{(1)} \times \dots \times \mathcal{S}^{(n)}$

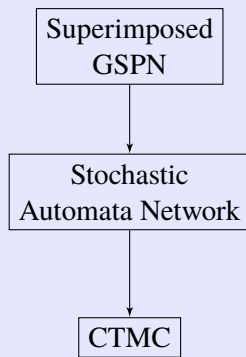
infinitesimal generator  $Q \in \mathbb{R}^{|\mathcal{PS}| \times |\mathcal{PS}|}$



finite state space  $\mathcal{S}$

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Lumping, MDD, Kronecker, Reachable

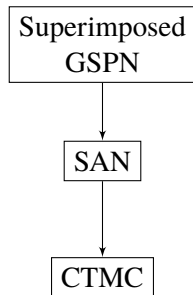


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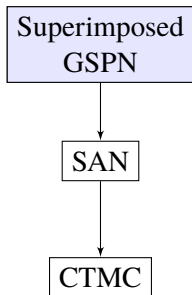
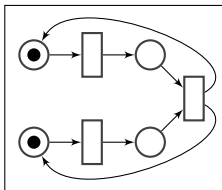
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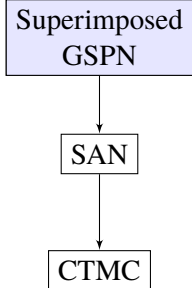
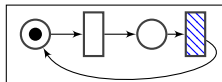
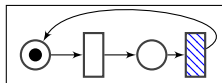
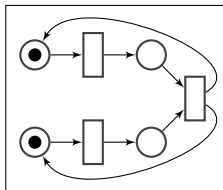
# Descriptor matrix



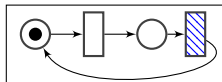
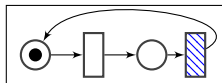
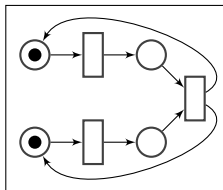
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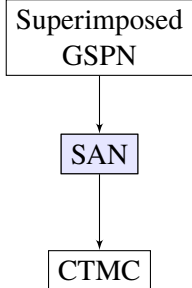
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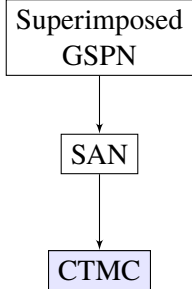
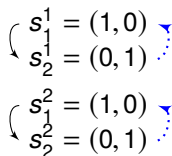
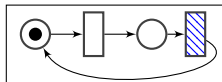
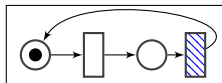
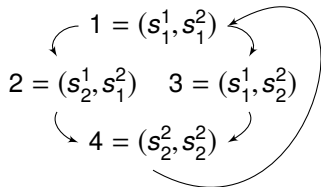
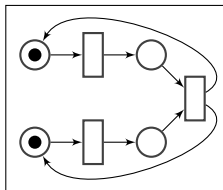
# Descriptor matrix



$$\begin{aligned} & \left\{ \begin{array}{l} s_1^1 = (1, 0) \\ s_2^1 = (0, 1) \end{array} \right. \\ & \left\{ \begin{array}{l} s_1^2 = (1, 0) \\ s_2^2 = (0, 1) \end{array} \right. \end{aligned}$$

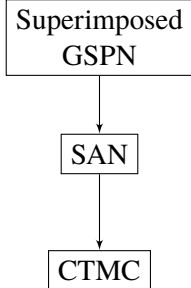
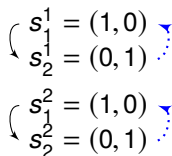
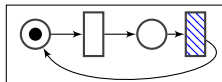
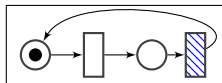
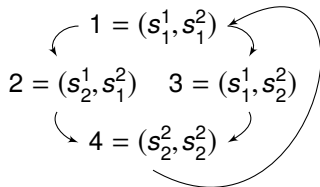
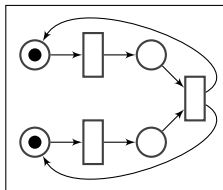


# Descriptor matrix

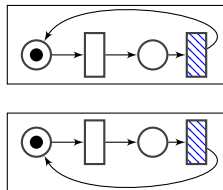
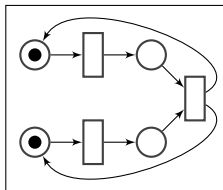




# Descriptor matrix



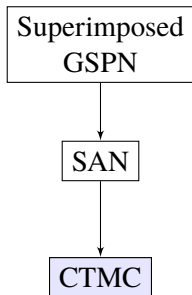
# Descriptor matrix



$$\begin{bmatrix} \times & \times \\ & \times \\ \times & \times \\ \times & \times \end{bmatrix} = \begin{bmatrix} \times \\ \times \\ \times \end{bmatrix} \oplus \begin{bmatrix} \times \\ \times \\ \times \end{bmatrix} + \begin{bmatrix} \times & 1 \\ 1 & \times \end{bmatrix} \otimes \begin{bmatrix} 1 & 1 \\ \times & 1 \end{bmatrix}$$

Descriptor matrix  $\quad R$   $\quad W$

local  $\quad$  synchronization



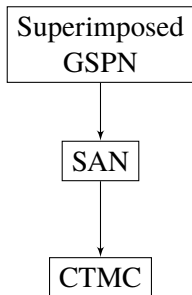
# Descriptor matrix

$$\text{steady-state } \pi \text{ s.t. } \begin{cases} \pi Q &= 0 \\ \pi \mathbb{1}^T &= 1 \end{cases}$$

$$\begin{bmatrix} & \times & \times & \\ & & & \times \\ & & & \times \\ \times & & & \end{bmatrix} = \begin{bmatrix} \times \\ \oplus \\ \times \end{bmatrix} + \begin{bmatrix} \times \\ \otimes \\ 1 \end{bmatrix} \otimes \begin{bmatrix} 1 \\ \times \\ 1 \end{bmatrix}$$

Descriptor matrix                      R                      W                      synchronization

local



# Descriptor vectors

- Recent development: compress both  $Q$  and  $\pi$  exploiting the Kronecker structure
  - Kressner, 2014: Tensor-Trains
  - Buchholz, 2017: Hierarchical Tucker Decomposition
- We followed Kressner

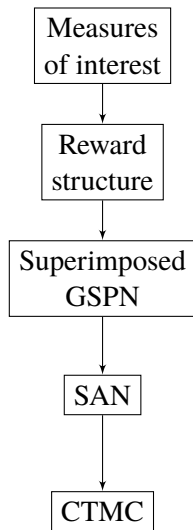
$$\mathcal{A}_{i_1 \dots i_d} = \underbrace{G_1[i_1]}_{1 \times r} \underbrace{G_2[i_2]}_{r \times r} \dots \underbrace{G_d[i_d]}_{r \times 1}$$

An example of computing one element of 4-dimensional tensor:

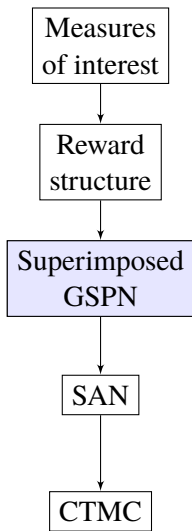
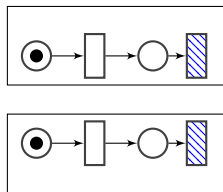
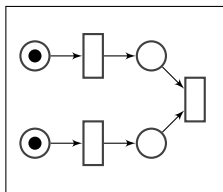
$$\mathcal{A}_{2423} = \begin{matrix} G_1 \\ \text{[red box]} \\ i_1 = 2 \end{matrix} \times \begin{matrix} G_2 \\ \text{[red grid]} \\ i_2 = 4 \end{matrix} \times \begin{matrix} G_3 \\ \text{[white grid]} \\ i_3 = 2 \end{matrix} \times \begin{matrix} G_4 \\ \text{[red box]} \\ i_4 = 3 \end{matrix}$$

- Standard iterative methods to evaluate  $\pi$  fail because in  $\pi^{k+1} = \pi^k + \delta\pi^k$  the TT-ranks can grow too quickly
- Thus, ad hoc solution methods have been designed

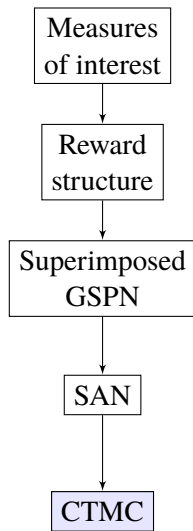
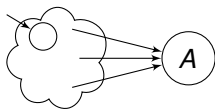
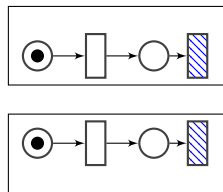
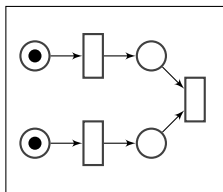
# CTMCs with an absorbing state



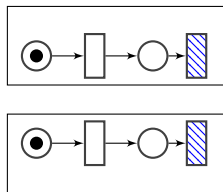
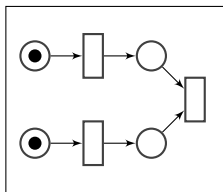
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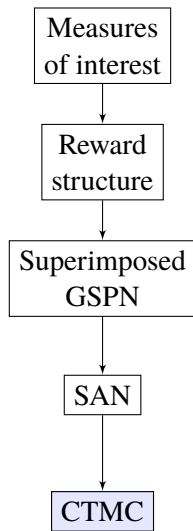
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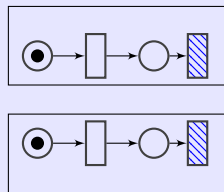
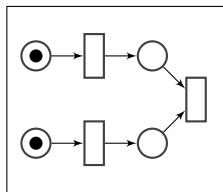


$$Q = \left[ \begin{array}{ccc|c} & & & v_1 \\ & \hat{Q} & & \vdots \\ & & & v_{N-1} \\ \hline 0 & \dots & 0 & 0 \end{array} \right]$$

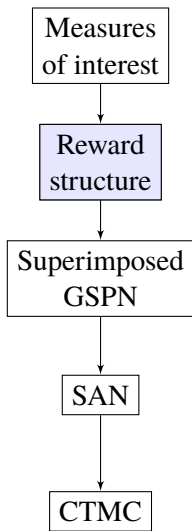




# CTMCs with an absorbing state



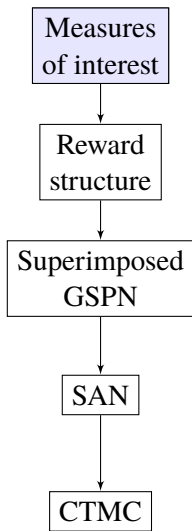
$$Q = \left[ \begin{array}{c|c} \hat{Q} & \begin{matrix} v_1 \\ \vdots \\ v_{N-1} \end{matrix} \\ \hline 0 \dots 0 & 0 \end{array} \right] \quad r = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \otimes \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \otimes \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$



# CTMCs with an absorbing state

$$\text{MTTA} = -\hat{\pi}_0 \hat{Q}^{-1} \mathbb{1}^T$$

$$Q = \left[ \begin{array}{c|c} \hat{Q} & \begin{matrix} v_1 \\ \vdots \\ v_{N-1} \end{matrix} \\ \hline 0 \dots 0 & 0 \end{array} \right] \quad r = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \otimes \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \otimes \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$



# Focus of the analysis

# Problems identification

- Shifting  $Q$  to obtain an irreducible CTMC as

$$\left[ \begin{array}{ccc|c} & & & v_1 \\ & \hat{Q} & & \vdots \\ & & & v_{N-1} \\ \hline 0 & 0 & \dots & 0 \end{array} \right] + \left[ \begin{array}{c|c} & \\ \hline 1 & -1 \end{array} \right]$$

assuming  $(\pi_0)_i \neq 0$  only for  $i = 1$ , introduces many difficulties

- If  $Q$  has a nice TT decomposition it is not guaranteed that  $\hat{Q}$  has a nice TT decomposition too
- Even a good compression (small TT-ranks) for  $\hat{Q}$  does not guarantee a good compression for the vectors involved in iterative solution methods

# Proposed solutions and new problems (I)

## Proposed solution:

- Define the **new** shift  $Q - S$  as

$$\left[ \begin{array}{ccc|c} & & & v_1 \\ & & & \vdots \\ & & & v_{N-1} \\ \hline 0 & 0 & \dots & 0 \end{array} \right] - \left[ \begin{array}{c|c} & v_1 \\ & \vdots \\ & v_{N-1} \\ \hline & -1 \end{array} \right]$$

- $Q - S$  and  $Q$  have the same Kronecker structure and the TT-ranks of  $S$  are  $(1, 1, \dots, 1)$
- We can solve the system with  $Q - S$  because

$$MTTA = -\hat{\pi}_0 \hat{Q}^{-1} \mathbb{1}^T = -\pi_0 (Q - S)^{-1} r^T,$$

provided that  $(\pi_0)_N = 0$

## Problem:

- The methods studied by Kressner and Buchholz do not work for  $Q - S$  because the TT-ranks grow too much anyway

## Proposed solutions and new problems (II)

### Proposed solution:

- Define a new **split**  $Q = Q_1 + Q_2$  such that

$$\begin{aligned} Q - S &= Q_1 + Q_2 - S = \underbrace{R + \Delta'}_{Q_1} + \underbrace{W + \Delta - \Delta'}_{Q_2} - S \\ &= Q_1 \left( I + Q_1^{-1}(Q_2 - S) \right) = Q_1 (I - M) \end{aligned}$$

where  $M = -Q_1^{-1}(Q_2 - S)$  and  $\Delta'$  is a suitable Kronecker sum of diagonal matrices (details in the paper)

- Exploit the Neumann series

$$(Q - S)^{-1} = (I - M)^{-1} Q_1^{-1} = Q_1^{-1} + M Q_1^{-1} + M^2 Q_1^{-1} + M^3 Q_1^{-1} + \dots = \sum_{j=0}^{\infty} M^j Q_1^{-1}$$

### Problem:

- Is this a convergent series?

## Proposed solutions and new problems (III)

### Proposed solution:

- Of course it is a convergent series (Theorem in the paper) because the spectral radius of  $M$ , called  $\rho(M)$ , is strictly less than 1

### Problem:

- Is the inversion of  $Q_1$  computationally cheaper than inverting  $Q - S$ ?

### Proposed solution:

- Consider the **exponential sums** approximation

$$\frac{1}{x} \approx \sum_{j=1}^{\ell} \alpha_j e^{-\beta_j x},$$

which has a controlled error bound on  $[1, +\infty)$

- Exploit the matrix exponential  $e^{Q_1} = I + \frac{1}{2}Q_1^2 + \frac{1}{6}Q_1^3 + \dots$
- Exploit the property  $e^{Q_1^1 \oplus \dots \oplus Q_1^n} = e^{Q_1^1} \otimes \dots \otimes e^{Q_1^n}$

# Putting all together

- The core of the computation is

$$MTTA = -\pi_0(Q - S)^{-1}r^T \approx -\pi_0x^k, \text{ where } \begin{cases} x^0 & = Q_1^{-1}r^T \\ x^{k+1} & = x^k + Mx^k \end{cases}$$

- The matrix-vector product is evaluated through

$$\begin{aligned} Mx &= -Q_1^{-1}(Q_2 - S)x = -(Q_1^1 \oplus \dots \oplus Q_1^n)^{-1}(\Delta - \Delta' + W - S)x \approx \\ &\approx \sum_{j=1}^{\ell} \alpha_j \left( e^{\beta_j(R^1 + \Delta'_1)} \otimes \dots \otimes e^{\beta_j(R^n + \Delta'_n)} \right) (\Delta - \Delta' + W - S)x, \end{aligned}$$

where all the matrices and  $x$  are in TT format.



# Safe approximation

## Remark

Notice that, defining  $z^{k+1} = Q_1^{-1}(Q_2 - S)z^k$  and  $z^0 = Q_1^{-1}(\mathbb{1} - e_N^T Q_1^{-1} \mathbb{1} \cdot e_N)$ , we obtain

$$MTTA = -\pi_0^T \cdot z^k + O(\rho(M)^{k+1}),$$

where  $z^{k+1} \geq z^k$  for all  $k = 0, 1, \dots$  because  $e_N^T z^0 = 0$  and both  $Q_1^{-1}$  and  $Q_2$  are non-negative matrices.

This means that the MTTA can be computed in a [safe way](#), being the approximation  $-\pi_0^T \cdot z^k$  a lower bound

# computations saving and acceleration techniques

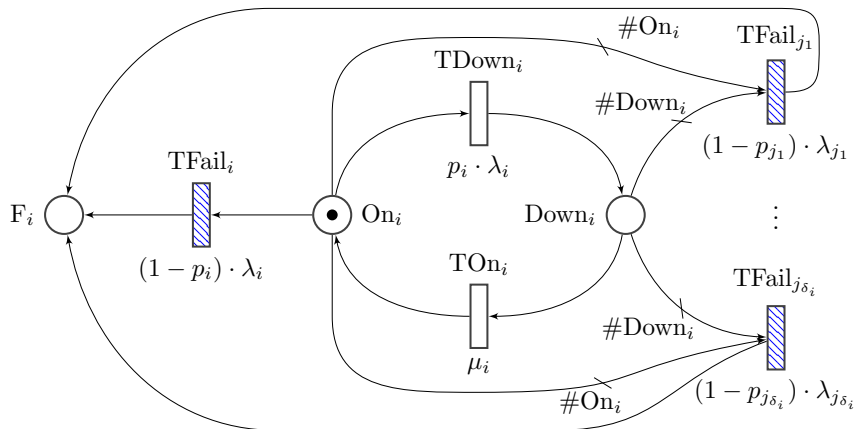
- Instead of implementing  $Mx$  we can work with  $M^T$  exploiting the fact that
  - from a state in  $\mathcal{S}$  we cannot reach a state in  $\mathcal{P}\mathcal{S} \setminus \mathcal{S}$
  - from a state in  $\mathcal{P}\mathcal{S} \setminus \mathcal{S}$  we can reach a state in  $\mathcal{S}$
- Consider the following series

$$(I - M)^{-1} = (I + M)(I + M^2) \cdots (I + M^{2^k}) \cdots$$

it is equivalent to the Neumann series, but converges quadratically

- Here we have to implement the matrix-matrix product instead of the matrix-vector product, and the TT-ranks can grow quickly

# Case study

GSPN for  $C_i$ 

The failure of  $C_i$  can impact on  $C_{j_1}, \dots, C_{j_{\delta_i}}$

# Evaluation results

- Consider  $n = 10, 20, \dots, 50$
- Number of potential states:  $|\mathcal{PS}| = 3^n$
- Topology of interactions is obtained as follows:
  - a star topology is constructed, where, labeling the nodes from 1 to  $n$ , there exist  $n - 1$  edges connecting 1 to  $j$ , for  $j = 2, \dots, n$
  - for each node with index greater than 1, another edge connecting it to a random node is added with probability 0.2

Such topologies are good representatives of topologies addressed by KAES: large number of components, loosely interconnected

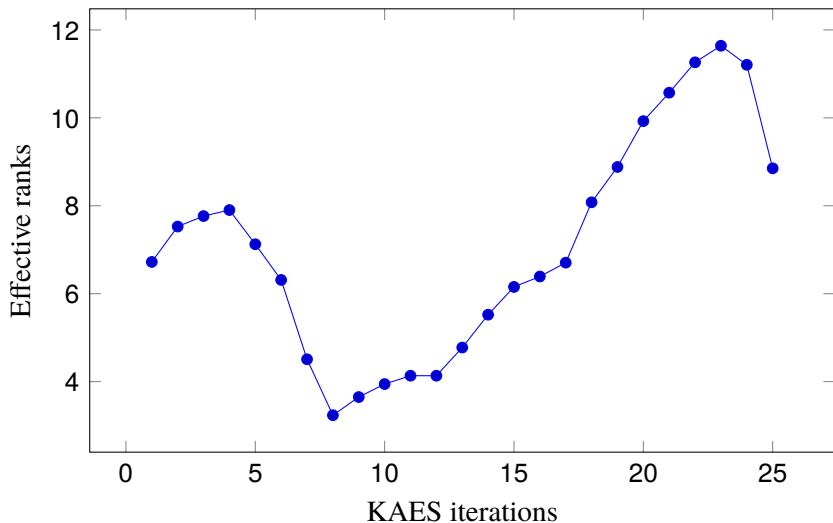
- The remaining parameters are chosen at random within the following intervals

$$\lambda_i \in [0.5, 1.5], \quad \mu_i \in [2000, 3000], \quad \rho \in [0.95, 1],$$

so that there are 4 orders of magnitude among the parameters. The tests have been repeated 100 times for each value of  $n$ , using the randomized topology described above

**Table:** Potential spaces dimensions, memory consumption, time and number of cases where the KAES approach was successful, where  $\mu$  reports the average over the 100 runs and  $\sigma$  is the standard deviation.

n	$\mathcal{PS}$	memory (Gb)		time (s)		% solved cases
		$\mu$	$\sigma$	$\mu$	$\sigma$	
10	59049	0.90	0.08	1.17	0.81	100%
20	$3.49 \cdot 10^9$	3.07	9.68	65.83	346.24	100%
30	$2.06 \cdot 10^{14}$	8.31	19.40	193.29	619.63	91%
40	$1.22 \cdot 10^{19}$	4.42	9.97	140.89	477.67	91%
50	$7.18 \cdot 10^{23}$	7.79	17.27	299.44	840.78	84%



**Figure:** Evolution of the effective ranks, representing an average of the TT-ranks of the carriages, for each iteration of KAES, with  $n = 20$  and a specific topology.



# Conclusions and future work

# Conclusions

- Analytical modeling of large, interconnected systems by developing a **new** numerical evaluation approach called KAES
- Focus on Mean Time To Absorption
- Symbolic representation of both the descriptor matrix and the descriptor vector to mitigate the state space explosion
- Although symbolic representation has been already applied in existing studies, such previous works focus on **steady-state analysis**
- KAES targets **limiting analysis in presence of absorbing states**
- The way MTTA is computed guarantees a **safe assessment**, which is relevant when dealing with dependability critical applications
- We started a numerical evaluation campaign, where the presented case study is the first step

## Future work

- More experiments are needed to better understand strengths and limitations of this new technique
- A deeper understanding of the link between TT-ranks and the topology of interactions among system components would be desirable
- The powerfulness of the adopted techniques make this method not restricted to the evaluation of MTTA only, but **adaptable** to evaluate general performability related indicators
- We are working on a general treatment of reward vectors to allow the modeler to define them at SGSPN level maintaining both the Kronecker structure and a good compression

## Future work

- We have recently published a new way of interpreting performability measures in terms of **matrix functions**
- Being able to evaluate efficiently  $f(\tilde{Q} - S)$  where

$$f(z) = \begin{cases} \frac{1}{z} & \text{if } z \neq 0, \\ 0 & \text{otherwise,} \end{cases}$$

is the first step to evaluate **transient** measures that can be expressed through

$$\varphi_j(z) = \begin{cases} \frac{\varphi_{j-1}(z)-1}{z} & \text{if } j > 1, \\ \frac{e^z-1}{z} & \text{if } j = 1. \end{cases}$$

Thank you  
Questions?